

NOTES - TRIGONOMETRY

Angles of Rotation in Standard Position

position is formed when an angle is in standard position. The initial side is on the **positive x-axis** and is rotated about the **vertex** to the terminal side.

How to measure an angle in standard position:

1. **measure** the angle in **Standard Position**.
2. **ray** along the **x-axis**.
3. **ray** that indicates the end of the angle.
4. **angle** whose vertex is at the origin on the **positive x-axis**.
5. An angle that rotates **Counter-clockwise**.
6. An angle that rotates **Clockwise**.

Example 1: Draw each angle in standard position.

45° 300°

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Coterminal & Reference Angles

Coterminal Angles

Any angles that have the same terminal side. They can find coterminal angles by adding or subtracting 360° .

Example 1: Find a positive and negative angle coterminal with 45° .

$45 + 360 = 405^\circ$ (positive)

$45 - 360 = -315^\circ$ (negative)

Example 2: Find a positive and negative angle coterminal with 120° .

$120 + 360 = 480^\circ$ (positive)

$120 - 360 = -240^\circ$ (negative)

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Trigonometric Functions of θ

Given a point P on the terminal side of θ in standard position, the distance from the origin to the point P is given by $r = \sqrt{x^2 + y^2}$.

Trigonometric Functions:

Function	Definition
SINE	$\sin \theta = \frac{y}{r}$
COSINE	$\cos \theta = \frac{x}{r}$
TANGENT	$\tan \theta = \frac{y}{x}$
SECANT	$\sec \theta = \frac{r}{x}$
CSCANT	$\csc \theta = \frac{r}{y}$
COTANGENT	$\cot \theta = \frac{x}{y}$

NOTES - TRIGONOMETRY

Signs in each Quadrant

The sign of the trigonometric functions of an angle in standard position can be determined by the sign of the x and y coordinates of the point P on the terminal side.

Quadrant	Signs
I	+
II	-
III	-
IV	+



2 Lesson B Angles Of Rotation

Chao Zhang



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Geometry Turned On James King, Doris Schattschneider, 1997-10-30 Articles about the uses of active exploratory geometry carried out with interactive computer software

Introduction to Geometrical Optics Milton Katz, 2002 This book is the culmination of twenty five years of teaching Geometrical Optics The volume is organised such that the single spherical refracting surface is the basic optical element Spherical mirrors are treated as special cases of refraction with the same applicable equations Thin lens equations follow as combinations of spherical refracting surfaces while the cardinal points of the thick lens make it equivalent to a thin lens Ultimately one set of vergence equations are applicable to all these elements The chapters are devoted to in depth treatments of stops pupils and ports magnifiers microscopes telescopes and camera lenses ophthalmic instruments resolving power and MTF trigonometric ray tracing and chromatic and monochromatic aberrations There are over 100 worked examples 400 homework problems and 400 illustrations First published in 1994 by Penumbra Publishing Co

Lessons in Geometry Jacques Hadamard, 2008 This is a book in the tradition of Euclidean synthetic geometry written by one of the twentieth century's great mathematicians The original audience was pre college teachers but it is useful as well to gifted high school students and college students in particular to mathematics majors interested in geometry from a more advanced standpoint The text starts where Euclid starts and covers all the basics of plane Euclidean geometry But this text does much more It is at once pleasingly classic and surprisingly modern The problems more than 450 of them are well suited to exploration using the modern tools of dynamic geometry software For this reason the present edition includes a CD of dynamic solutions to select problems created using Texas Instruments TI Nspire Learning Software The TI Nspire documents demonstrate connections among problems and through the free trial software included on the CD will allow the reader to explore and interact with Hadamard's Geometry in new ways The material also includes introductions to several advanced topics The exposition is spare giving only the minimal background needed for a student to explore these topics Much of the value of the book lies in the problems whose solutions open worlds to the engaged reader And so this book is in the Socratic tradition as well as the Euclidean in that it demands of the reader both engagement and interaction A forthcoming companion volume that includes solutions extensions and classroom activities related to the problems can only begin to open the treasures offered by this work We are just fortunate that one of the greatest mathematical minds of recent times has made this effort to show to readers some of the opportunities that the intellectual tradition of Euclidean geometry has to offer Jacket

Lighting Fundamentals Course,

ED-2, Including Supplement to Lesson VI, Zonal Cavity Method Illuminating Engineering Society. Committee on Lighting Education, 1961

A Student's Guide to Python for Physical Modeling Jesse M. Kinder, Philip Nelson, 2018-01-30 A fully updated tutorial on the basics of the Python programming language for science students Python is a computer programming language that is rapidly gaining popularity throughout the sciences This fully updated edition of A Student's Guide to Python for Physical Modeling aims to help you the student teach yourself enough of the Python programming language to get started with physical modeling You will learn how to install an open source Python programming environment and use it to accomplish many common scientific computing tasks importing exporting and visualizing data numerical analysis and simulation No prior programming experience is assumed This tutorial focuses on fundamentals and introduces a wide range of useful techniques including Basic Python programming and scripting Numerical arrays Two and three dimensional graphics Monte Carlo simulations Numerical methods including solving ordinary differential equations Image processing Animation Numerous code samples and exercises with solutions illustrate new ideas as they are introduced Web based resources also accompany this guide and include code samples data sets and more This current edition brings the discussion of the Python language Spyder development environment and Anaconda distribution up to date In addition a new appendix introduces Jupyter notebooks

Quaternions and Rotation Sequences J. B. Kuipers, 2020-03-31 Ever since the Irish mathematician William Rowan Hamilton introduced quaternions in the nineteenth century a feat he celebrated by carving the founding equations into a stone bridge mathematicians and engineers have been fascinated by these mathematical objects Today they are used in applications as various as describing the geometry of spacetime guiding the Space Shuttle and developing computer applications in virtual reality In this book J B Kuipers introduces quaternions for scientists and engineers who have not encountered them before and shows how they can be used in a variety of practical situations The book is primarily an exposition of the quaternion a 4 tuple and its primary application in a rotation operator But Kuipers also presents the more conventional and familiar 3×3 element matrix rotation operator These parallel presentations allow the reader to judge which approaches are preferable for specific applications The volume is divided into three main parts The opening chapters present introductory material and establish the book's terminology and notation The next part presents the mathematical properties of quaternions including quaternion algebra and geometry It includes more advanced special topics in spherical trigonometry along with an introduction to quaternion calculus and perturbation theory required in many situations involving dynamics and kinematics In the final section Kuipers discusses state of the art applications He presents a six degree of freedom electromagnetic position and orientation transducer and concludes by discussing the computer graphics necessary for the development of applications in virtual reality

Aviation Instructor's Handbook United States. Federal Aviation Administration, 1977

Computer Animation Rick Parent, 2012-10-18 Driven by demand from the entertainment industry for better and more realistic animation technology continues to evolve and improve The algorithms

and techniques behind this technology are the foundation of this comprehensive book which is written to teach you the fundamentals of animation programming In this third edition the most current techniques are covered along with the theory and high level computation that have earned the book a reputation as the best technically oriented animation resource Key topics such as fluids hair and crowd animation have been expanded and extensive new coverage of clothes and cloth has been added New material on simulation provides a more diverse look at this important area and more example animations and chapter projects and exercises are included Additionally spline coverage has been expanded and new video compression and formats e g iTunes are covered Includes companion site with contemporary animation examples drawn from research and entertainment sample animations and example code Describes the key mathematical and algorithmic foundations of animation that provide you with a deep understanding and control of technique Expanded and new coverage of key topics including fluids and clouds cloth and clothes hair and crowd animation Explains the algorithms used for path following hierarchical kinematic modelling rigid body dynamics flocking behaviour particle systems collision detection and more

Handbook of Mathematics Vialar Thierry, 2023-08-22 The book revised consists of XI Parts and 28 Chapters covering all areas of mathematics It is a tool for students scientists engineers students of many disciplines teachers professionals writers and also for a general reader with an interest in mathematics and in science It provides a wide range of mathematical concepts definitions propositions theorems proofs examples and numerous illustrations The difficulty level can vary depending on chapters and sustained attention will be required for some The structure and list of Parts are quite classical I Foundations of Mathematics II Algebra III Number Theory IV Geometry V Analytic Geometry VI Topology VII Algebraic Topology VIII Analysis IX Category Theory X Probability and Statistics XI Applied Mathematics Appendices provide useful lists of symbols and tables for ready reference Extensive cross references allow readers to find related terms concepts and items by page number heading and objet such as theorem definition example etc The publisher s hope is that this book slightly revised and in a convenient format will serve the needs of readers be it for study teaching exploration work or research

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