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Gender	Male	Female	Title		
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Email Address					
Citizenship	SA	Other	Degree registered	Master's	Part-time
				D doctoral	Full-time
Month and year of first registration					
Have you applied for other bursaries?				Yes	No
Other bursary: Name and Value					
Name of Host				Date	
Head of Department				Date	
HFA				Date	
Student Signature				Date	

Recommendation			
Host's Signature		Date	
Faculty Representative		Date	

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The Obligation to Extradite Or Prosecute Kriangsak Kittichaisaree,2018 It was hoped that the creation of the International Criminal Court would enable the extradition and prosecution of crimes which shock the world Fifteen years later Kittichaisaree scrutinises the achievements and limitations of the court so far offering his own vision for ensuring that no international criminal escapes the eye of justice

Universal Jurisdiction over Core International Crimes Lachezar Yanev,Harmen van der Wilt,2025-09-10 This timely book explores how the domestic courts of states across Europe North America and Oceania have defined and applied their substantive laws in universal jurisdiction trials for core international crimes It considers what universal justice actually looks like in the national courtrooms of diverse states and probes the extent to which there is uniformity in the pursuit to punish universally condemned crimes

Information Science and Applications 2018 Kuinam J. Kim,Nakhon Baek,2018-07-23 This book contains selected papers from the 9th International Conference on Information Science and Applications ICISA 2018 and provides a snapshot of the latest issues encountered in technical convergence and convergences of security technology It explores how information science is core to most current research industrial and commercial activities and consists of contributions covering topics including Ubiquitous Computing Networks and Information Systems Multimedia and Visualization Middleware and Operating Systems Security and Privacy Data Mining and Artificial Intelligence Software Engineering and Web Technology The proceedings introduce the most recent information technology and ideas applications and problems related to technology convergence illustrated through case studies and reviews converging existing security techniques Through this volume readers will gain an understanding of the current state of the art information strategies and technologies of convergence security The intended readership includes researchers in academia industry and other research institutes focusing on information science and technology

Quality Control Applications in the Pharmaceutical and Medical Device Manufacturing Industry Carrillo-Cedillo, Eugenia Gabriela,Arredondo-Soto, Karina Cecilia,Palomino-Vizcaino, Kenia,Magaña-Badilla, Héctor Alfonso,2022-03-18 Quality control in pharmaceutical products and medical devices is vital for users as failing to comply with national and international regulations can lead to accidents that could easily be avoided For this reason manufacturing a quality medical product will support patient safety Microbiologists working in both the pharmaceutical and medical device industries face considerable challenges in keeping abreast of the myriad microbiological references available to them and the continuously evolving regulatory requirements Quality Control Applications in the Pharmaceutical and Medical Device Manufacturing Industry presents the importance of quality control in pharmaceutical products and medical devices which

must have very high quality standards to not cause problems to the health of patients It reinforces and updates the knowledge of analytical instrumental and biological methods to demonstrate the correct quality control and good manufacturing practice for pharmaceutical products and medical devices Covering topics such as pharmaceutical nano systems machine learning and software validation this book is an essential resource for managers engineers supervisors pharmacists chemists academicians and researchers

A New Generation Material Graphene: Applications in Water Technology Mu. Naushad, 2018-06-20 This book presents a unique collection of up to date applications of graphene for water science Because water is an invaluable resource and the intelligent use and maintenance of water supplies is one of the most important and crucial challenges that stand before mankind new technologies are constantly being sought to lower the cost and footprint of processes that make use of water resources as potable water as well as water for agriculture and industry which are always in desperate demand Much research is focused on graphene for different water treatment uses Graphene whose discovery won the 2010 Nobel Prize in physics has been a shining star in the material science in the past few years Owing to its interesting electrical optical mechanical and chemical properties graphene has found potential applications in a wide range of areas including water purification technology A new type of graphene based filter could be the key to managing the global water crisis According to the World Economic Forum s Global Risks Report lack of access to safe clean water is the biggest risk to society over the coming decade Yet some of these risks could be mitigated by the development of this filter which is so strong and stable that it can be used for extended periods in the harshest corrosive environments and with less maintenance than other filters on the market The graphene based filter could be used to filter chemicals viruses or bacteria from a range of liquids It could be used to purify water dairy products or wine or in the production of pharmaceuticals This book provides practical information to all those who are involved in this field

Mathematical Applications in Continuum and Structural Mechanics Francesco Marmo, Salvatore Sessa, Emilio Barchiesi, Mario Spagnuolo, 2021-11-30 This book presents a range of research projects focusing on innovative numerical and modeling strategies for the nonlinear analysis of structures and metamaterials The topics covered concern various analysis approaches based on classical finite element solutions structural optimization and analytical solutions in order to present a comprehensive overview of the latest scientific advances Although based on pioneering research the contributions are focused on immediate and direct application in practice providing valuable tools for researchers and practicing professionals alike

An African Criminal Court Dominique Mystris, 2020-11-30 In An African Criminal Court Dominique Mystris explores the potential contribution of a regional criminal court to international criminal law and justice across the continent As set out in the Malabo Protocol the court s approach to international core crimes builds on from the current international system Yet the additional crimes and region centric approach reflect the continental concerns To fully realise the court s contribution the African Union s institutional objectives and approach to justice peace and security the author argues for the

inclusion of the court within the African Peace and Security Architecture By adopting such a holistic understanding of the Malabo Protocol court within the AU structure a more accurate depiction of the potential of an African criminal court emerges

Motion planning and feedback control techniques with applications to long tractor-trailer vehicles Oskar Ljungqvist, 2020-04-20

During the last decades improved sensor and hardware technologies as well as new methods and algorithms have made self driving vehicles a realistic possibility in the near future At the same time there has been a growing demand within the transportation sector to increase efficiency and to reduce the environmental impact related to transportation of people and goods Therefore many leading automotive and technology companies have turned their attention towards developing advanced driver assistance systems and self driving vehicles Autonomous vehicles are expected to have their first big impact in closed environments such as mines harbors loading and offloading sites In such areas the legal requirements are less restrictive and the surrounding environment is more controlled and predictable compared to urban areas Expected positive outcomes include increased productivity and safety reduced emissions and the possibility to relieve the human from performing complex or dangerous tasks Within these sites tractor trailer vehicles are frequently used for transportation These vehicles are composed of several interconnected vehicle segments and are therefore large complex and unstable while reversing This thesis addresses the problem of designing efficient motion planning and feedback control techniques for such systems The contributions of this thesis are within the area of motion planning and feedback control for long tractor trailer combinations operating at low speeds in closed and unstructured environments It includes development of motion planning and feedback control frameworks structured design tools for guaranteeing closed loop stability and experimental validation of the proposed solutions through simulations lab and field experiments Even though the primary application in this work is tractor trailer vehicles many of the proposed approaches can with some adjustments also be used for other systems such as drones and ships The developed sampling based motion planning algorithms are based upon the probabilistic closed loop rapidly exploring random tree CL RRT algorithm and the deterministic lattice based motion planning algorithm It is also proposed to use numerical optimal control offline for precomputing libraries of optimized maneuvers as well as during online planning in the form of a warm started optimization step To follow the motion plan several predictive path following control approaches are proposed with different computational complexity and performance Common for these approaches are that they use a path following error model of the vehicle for future predictions and are tailored to operate in series with a motion planner that computes feasible paths The design strategies for the path following approaches include linear quadratic LQ control and several advanced model predictive control MPC techniques to account for physical and sensing limitations To strengthen the practical value of the developed techniques several of the proposed approaches have been implemented and successfully demonstrated in field experiments on a full scale test platform To estimate the vehicle states needed for control a novel nonlinear observer is evaluated on the full scale test vehicle It is designed to only utilize

information from sensors that are mounted on the tractor making the system independent of any sensor mounted on the trailer Under de senaste årtiondena har utvecklingen av sensor och hördvaruteknik gått i en snabb takt samtidigt som nya metoder och algoritmer har introducerats Samtidigt ställs det stora krav på transportsektorn att öka effektiviteten och minska miljöpåverkan vid transporter av både människor och varor Som en följd av detta har många ledande fordonstillverkare och tekniska företag redan satsat på att utveckla avancerade fjärrstyrsystem och självkörande fordon Vissa forskningen inom autonoma fordon har under de senaste årtiondena kraftigt ökat den tekniska problemställningen är att låsa fast fordon förväntas sitt första stora genombrott i slutna miljöer såsom gruvor hamnar lastnings och lossningsplatser I sådana områden är lagstiftningen mindre hördjupad jämfört med stadsområden och omgivningen är mer kontrollerad och förutsägbare Några av de förväntade positiva effekterna är ökad produktivitet och säkerhet minskade utsläpp och möjligheten att avlasta människor från att utföra svåra eller farliga uppgifter Inom dessa platser används ofta lastbilar med olika släpvagnskombinationer för att transportera material En sådan fordonskombination är uppbyggd av flera ihopkopplade moduler och är således utmanande att backa då systemet är instabilt Detta gör det svårt att utforma ramverk för att styra sådana system vid exempelvis autonom backning Självkörande fordon är mycket komplexa system som består av en rad olika komponenter vilka är designade för att lösa separata delproblem Två viktiga komponenter i ett självkörande fordon är dels fjärrplaneraren som har i uppgift att planera hur fordonet ska röra sig för att på ett säkert sätt nå ett förordnat mål och dels den banföljande regulatorn vars uppgift är att se till att den planerade manövern faktiskt utförs i praktiken trots störningar och modellfel I denna avhandling presenteras flera olika algoritmer för att planera och utföra komplexa manövrer för lastbilar med olika typer av släpvagnskombinationer De presenterade algoritmerna är avsedda att användas som avancerade fjärrstyrsystem eller som komponenter i ett helt autonomt system Vissa områdena i denna avhandling är lastbilar med släpkan många av de föreslagna algoritmerna kan även användas för en rad andra system såsom drönare och bilar Experimentell validering är viktigt för att motivera att en föreslagen algoritm är användbar i praktiken I denna avhandling har flera av de föreslagna planerings och reglerstrategierna implementerats på en småskalig testplattform och utvärderats i en kontrollerad labbmiljö Utöver detta har även flera av de föreslagna ramverken implementerats och utvärderats i ett experiment på en fullskalig testplattform som har utvecklats i samarbete med Scania CV Huvudutvärderas även en ny metod för att skatta släpvagnens beteende genom att endast utnyttja information från sensorer monterade på lastbilen vilket gör det föreslagna ramverket oberoende av sensorer monterade på släpvagnen

Real-Time Recursive Hyperspectral Sample and Band Processing Chein-I Chang, 2017-04-23 This book explores recursive architectures in designing progressive hyperspectral imaging algorithms In particular it makes progressive imaging algorithms recursive by introducing the concept of Kalman filtering in algorithm design so that hyperspectral imagery can be processed not only progressively sample by sample or band by band but also recursively via recursive equations This book can be considered a companion book of author's books Real Time Progressive Hyperspectral Image Processing published by Springer in 2016

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