

NOTES - TRIGONOMETRY

Angles of Rotation

Standard Position

position is formed when an angle is in standard position. The initial side is on the **positive x-axis** and is rotated about the **vertex** to the terminal side.

How to measure an angle in Standard Position:

1. **measure** when angle is **Standard Position**.
2. **ray** along the **x-axis**.
3. **ray** that indicates the end of the angle.
4. **angle** whose vertex is at the origin and whose sides are on the **positive x-axis**.
5. An angle that rotates **Counter-clockwise**.
6. An angle that rotates **Clockwise**.

Example 1: Draw each angle in standard position.

45° 300°

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Coterminal & Reference Angles

Coterminal Angles

Any angles that have the same terminal side. They can find coterminal angles by adding or subtracting 360° .

Example 1: Find a positive and negative coterminal angle for 45° .

$45^\circ + 360^\circ = 405^\circ$ (positive)

$45^\circ - 360^\circ = -315^\circ$ (negative)

Example 2: Find a positive and negative coterminal angle for 120° .

$120^\circ + 360^\circ = 480^\circ$ (positive)

$120^\circ - 360^\circ = -240^\circ$ (negative)

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Trigonometric Functions of θ

Given a point P on the terminal side of θ in standard position, the distance from the origin to the point P is given by $r = \sqrt{x^2 + y^2}$.

Trigonometric Functions:

- SINE:** $\sin \theta = \frac{y}{r}$
- COSINE:** $\cos \theta = \frac{x}{r}$
- TANGENT:** $\tan \theta = \frac{y}{x}$
- SECANT:** $\sec \theta = \frac{r}{x}$
- CSCANT:** $\csc \theta = \frac{r}{y}$
- COTANGENT:** $\cot \theta = \frac{x}{y}$

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Signs in each Quadrant

The sign of the trigonometric functions of θ depends on the quadrant that the terminal side of θ lies in. Here is the sign of the trigonometric functions of θ in each quadrant.

Quadrant	I	II	III	IV
Sine	+	+	-	-
Cosine	+	-	-	+
Tangent	+	-	+	-
Cosecant	+	+	-	-
Secant	+	-	-	+
Cotangent	+	-	+	-



10 2 Lesson B Angles Of Rotation

Disha Experts

A red circular graphic with a gradient, appearing as a semi-circle or a partial circle, located to the right of the 'Disha Experts' text.

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Angular Momentum William J. Thompson, 2008-09-26 Develops angular momentum theory in a pedagogically consistent way starting from the geometrical concept of rotational invariance Uses modern notation and terminology in an algebraic approach to derivations Each chapter includes examples of applications of angular momentum theory to subjects of current interest and to demonstrate the connections between various scientific fields which are provided through rotations Includes Mathematica and C language programs *Mathematical Structures for Computer Graphics* Steven J. Janke, 2014-11-03 A comprehensive exploration of the mathematics behind the modeling and rendering of computer graphics scenes Mathematical Structures for Computer Graphics presents an accessible and intuitive approach to the mathematical ideas and techniques necessary for two and three dimensional computer graphics Focusing on the significant mathematical results the book establishes key algorithms used to build complex graphics scenes Written for readers with various levels of mathematical background the book develops a solid foundation for graphics techniques and fills in relevant graphics details often overlooked in the literature Rather than use a rigid theorem proof approach the book provides a flexible discussion that moves from vector geometry through transformations curve modeling visibility and lighting models Mathematical Structures for Computer Graphics also includes Numerous examples of two and three dimensional techniques along with numerical calculations Plenty of mathematical and programming exercises in each chapter which are designed particularly for graphics tasks Additional details at the end of each chapter covering historical notes further calculations and connected concepts for readers who wish to delve deeper Unique coverage of topics such as calculations with homogeneous coordinates computational geometry for polygons use of barycentric coordinates various descriptions for curves and L system techniques

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The Jahn-Teller Effect in C60 and Other Icosahedral Complexes

C. C. Chancey, M. C.M. O'Brien, 2021-02-09 Because of the high symmetry involved the Jahn Teller effect is the natural starting point for considering electron phonon or vibronic interactions in icosahedral molecules This work is the first comprehensive theoretical analysis of the Jahn Teller interaction in C60 and other icosahedral complexes The importance of this research derives in part from the increasing widespread interest in C60 and other molecular clusters and their application in science and industry The electrical and spectroscopic properties of fullerene and fulleride compounds depend intimately on the coupling between the electronic and vibrational modes of these systems and this book addresses the fundamental theoretical questions In particular a chapter is devoted to the connection between the theory and experimental observations such as ESR electron spin resonance effects and molecular spectra Earlier books have discussed the theory of Jahn Teller interactions in lower symmetry structures cubic tetrahedral tetragonal trigonal this is the first that focuses on the new icosahedral systems whose most famous example is Buckminsterfullerene C60 The book's authors have over fifty years of combined research experience into the theoretical aspects of the Jahn Teller effect

Quaternions and Rotation

Sequences J. B. Kuipers, 2020-03-31 Ever since the Irish mathematician William Rowan Hamilton introduced quaternions in the nineteenth century a feat he celebrated by carving the founding equations into a stone bridge mathematicians and engineers have been fascinated by these mathematical objects Today they are used in applications as various as describing the geometry of spacetime guiding the Space Shuttle and developing computer applications in virtual reality In this book J B Kuipers introduces quaternions for scientists and engineers who have not encountered them before and shows how they can be used in a variety of practical situations The book is primarily an exposition of the quaternion a 4 tuple and its primary application in a rotation operator But Kuipers also presents the more conventional and familiar 3 x 3 9 element matrix rotation operator These parallel presentations allow the reader to judge which approaches are preferable for specific applications The volume is divided into three main parts The opening chapters present introductory material and establish the book's terminology and notation The next part presents the mathematical properties of quaternions including quaternion algebra and geometry It includes more advanced special topics in spherical trigonometry along with an introduction to quaternion calculus and perturbation theory required in many situations involving dynamics and kinematics In the final section Kuipers discusses state of the art applications He presents a six degree of freedom electromagnetic position and orientation transducer and concludes by discussing the computer graphics necessary for the development of applications in virtual reality

Introduction to Robotics

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employ today and provides insights into the code employed. As such it offers a valuable resource for anyone interested in multicopters including students, teachers, researchers and engineers. This introductory text is a welcome addition to the literature on multicopter design and control on which the author is an acknowledged authority. The book is directed to advanced undergraduate and beginning graduate students in aeronautical and control or electrical engineering as well as to multicopter designers and hobbyists. Professor W. Murray Wonham, University of Toronto. This is the single best introduction to multicopter control. Clear, comprehensive and progressing from basic principles to advanced techniques, it's a must read for anyone hoping to learn how to design flying robots. Chris Anderson, 3D Robotics CEO.

Fundamentals of Physics, Extended David Halliday, Robert Resnick, Jearl Walker, 2013-08-05. The 10th edition of Halliday's Fundamentals of Physics. Extended building upon previous issues by offering several new features and additions. The new edition offers most accurate, extensive and varied set of assessment questions of any course management program in addition to all questions including some form of question assistance including answer specific feedback to facilitate success. The text also offers multimedia presentations, videos and animations of much of the material that provide an alternative pathway through the material for those who struggle with reading scientific exposition. Furthermore, the book includes math review content in both a self-study module for more in-depth review and also in just-in-time math videos for a quick refresher on a specific topic. The Halliday content is widely accepted as clear, correct and complete. The end-of-chapter problems are without peer. The new design which was introduced in 9e continues with 10e making this new edition of Halliday the most accessible and reader-friendly book on the market. WileyPLUS sold separately from text.

MODERN INERTIAL SENSORS AND SYSTEMS BOSE, AMITAVA, PURI, SOMNATH, BANERJEE, PARITOSH, 2008-03-09. Modern inertial sensors and systems cover more than five decades of continuous research and development involving various branches of science and engineering. Various technologies have emerged in an evolutionary manner surpassing the earlier ones in performance and reliability. The subject is still growing with proliferation in newer cost-effective applications while its wider usage in aerospace systems continues. This book exposes the readers to the subject of inertial navigation, the inertial sensors and inertial systems in a unified manner while emphasizing the growth areas in emerging technologies such as micro-electromechanical inertial sensors, satellite navigation, satellite navigation integrated inertial navigation, hemispherical resonator gyro, vibrating beam accelerometer, interferometric fibre optic gyro, inertial sensor signal processing, redundant inertial systems and the quite recent emergence of cold atom interferometer-based inertial sensors. The contents are imaginatively designed that will be of interest to a wide spectrum of readers. The book has been written with utmost lucidity and clarity and explanations provided with a large number of illustrative figures. Besides being an ideal introduction to the principles of inertial sensors and systems for undergraduate and postgraduate students of aerospace engineering, the topics dealt with will also be of benefit to practising engineers and can assist the researchers to locate excellent references for research work. The authors have had three

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