

Chapter 2

- The equation of the line tangent to the graph of $f(x) = x^2 + 3x$ at $x = 2$ is
 A) $y = 7x - 4$ B) $y = 7x - 422$ C) $y = 7x - 2$ D) $y = 7x - 144$
 Ans: A Difficulty: moderate Section: 2.1
- The equation of the line tangent to the graph of $f(x) = x^2 + 4x$ at $x = 3$ is
 A) $y = 10x - 9$ B) $y = 10x - 108$ C) $y = 10x - 3$ D) $y = 10x - 27$
 Ans: A Difficulty: moderate Section: 2.1
- The equation of the line tangent to the graph of $f(x) = 3\sqrt{x}$ at $x = 1$ is
 A) $y = \frac{1}{2}x + \frac{1}{2}$ B) $y = \frac{1}{2}x + \frac{1}{2}$ C) $y = \frac{3}{2}x + \frac{3}{2}$ D) $y = \frac{3}{2}x + 1$
 Ans: C Difficulty: moderate Section: 2.1
- For $f(x) = 5 - x^2$, find the slope of the secant line connecting the points whose x -coordinates are $x = -6$ and $x = -5.9$. Then use calculus to find the slope of the line that is tangent to the graph of f at $x = -6$.
 Ans: Slope of secant line: 11.9; Slope of tangent line: 12
 Difficulty: moderate Section: 2.1
- For $f(x) = -\frac{3}{\sqrt{x}}$, find the average rate of change of $f(x)$ with respect to x as x changes from 144 to 145. Then use calculus to find the instantaneous rate of change at $x = 144$. Round your answer to six decimal places, if necessary.
 A) Average rate of change: 0.000864; Instantaneous rate of change: -0.125
 B) Average rate of change: -0.000864; Instantaneous rate of change: 0.000868
 C) Average rate of change: -0.000864; Instantaneous rate of change: 0.125
 D) Average rate of change: 0.000864; Instantaneous rate of change: 0.000868
 Ans: D Difficulty: hard Section: 2.1
- If $f(x)$ represents the price per barrel of oil in terms of time, what does $\frac{f(x_0 + h) - f(x_0)}{h}$ represent? What about $\lim_{h \rightarrow 0} \frac{f(x_0 + h) - f(x_0)}{h}$?
 Ans: The average rate of change of oil price with respect to time on the time interval $[x_0, x_0 + h]$; the instantaneous rate of change of oil price with respect to time at time x_0 .
 Difficulty: easy Section: 2.1
- True or False: Differentiating $f(x) = x^3 + 3x + 1$ gives $3x^2$.
 A) True B) False
 Ans: B Difficulty: easy Section: 2.2

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Jeffrey Slater



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web fig 4 block diagram of mobile operated pickk and place robo the main part of the project is mechanical arrangement of robot arm by using 3 motors we can develop the robot arm with help of 4 or 5 motors according to our design in this project we used only 3 motors for controlling robot arm the below diagram shows the robot arm arrangement

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web block diagram showing receiver of a pick n place robot the system consists of two motors for providing motion to the whole robot and two other motors to provide the arm motion the end effector or the gripper needs to be controlled to apply proper pressure on the object to handle it effectly to give it a soft grip

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web here programmable logic and controller is used for controlling and operating robotic arm all the various problems of this

process have been analyzed properly and have been taken into consideration while programming and designing the pick and place robotic arm keywords automation plc pick and place robotic arm

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web based on the user commands the robot moves and pick and place the objects the robotic arm used here is similar to a human arm which is programmed to perform the pick and place functions the remainder of this paper is organized as follows the section 2 provides information about the existing works section 3 gives details of the proposed

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web block diagram of the 3 axis pick and place robot you will the following documents with this project project report in pdf format and in word format doc or docx circuit diagram pcb layout microcontroller program in assembly language hex file of the microcontroller code datasheets of all the components ics used in the project

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web pick and place robot module block diagram 14 3 3 1 robotic arm design the robotic arm with gripper termination has five degrees of freedom with a rotating base that rests on the upper region of the vehicle as depicted in figure 6